

Sparse Based Image Processing

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① Regularized Image Recovery

①.1 [ex: Image Denoising $Hx = y$
Noisy: $\min_x \frac{1}{2} \|Hx - y\|_2^2 + \frac{\alpha}{2} \|x\|_2^2$

[ex: Subsample MRI (single coil)
 $y = Ax = MFx$. $\text{rank}(A) < n$
A not invertible .
Need prior information to fill in the gaps...

①.2 MAP formulation $\Rightarrow$ Energy Min formulation

$\hookrightarrow y \sim \mathcal{N}(Ax, \sigma^2 I)$, $x \sim p(x)$

$\hookrightarrow$ equivalently $y \sim p(y|x)$

$\hookrightarrow p(x|y) \propto p(y|x) p(x)$.

↳ Analytical solve? → Yes → great.

↳ No? Need Numerical solve. ex. GD.

↳ When do we have a unique solution?

↳ convex loss function:

1.3 Sparse Priors

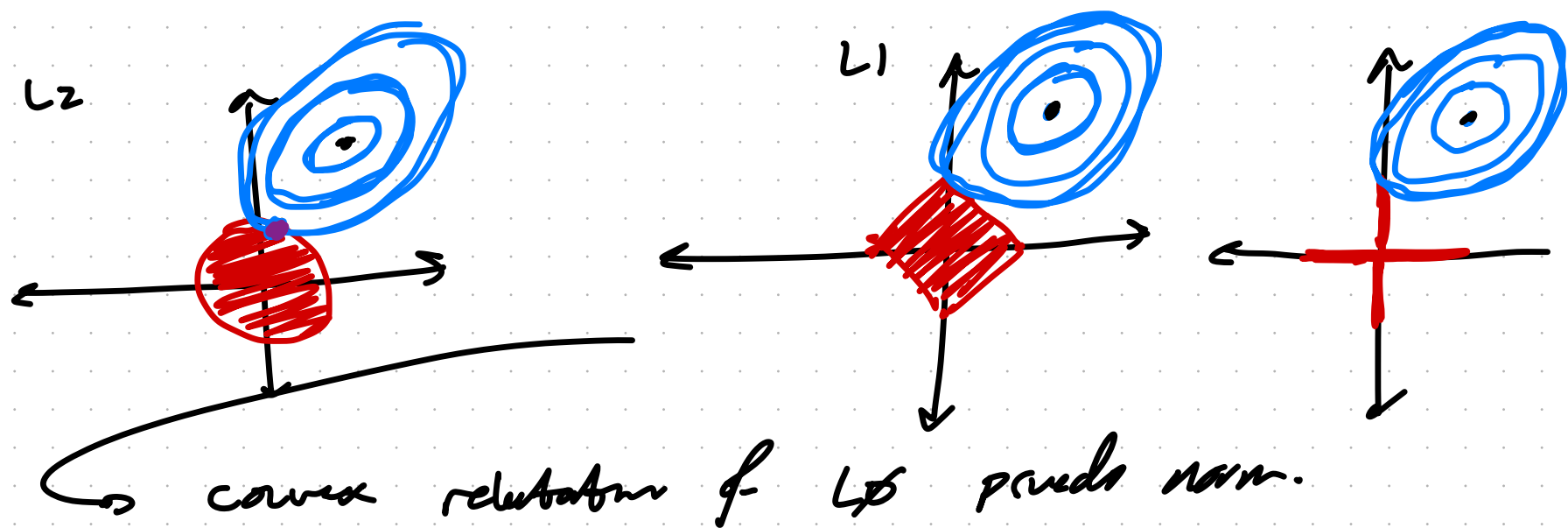
↳ ^① Wavelet Sparsity ^② $\phi = \|Wx\|_1$

↳ Total Variation $\phi = \|\nabla x\|_1$, $\phi = \|\nabla x\|_{2,1}$

↳ TGV

^① How do we encode sparsity?

→



So solve $x^* = \arg \min \frac{1}{2} \|y - Hx\|_2^2 + \phi(x)$

where $\phi = \|Wx\|_1$.

Convex? ✓

Differentiable?

- 1) Sub GD
- 2) Prox GD (ISTA)
- 3) ADMM.
- 11) PDS

① Signal/Image Recovery

We want to recover x from some measurement y .

Linear Measurements: $y = Hx$.

ex. Blurring: $Hx = h * x$ (conv)

ex. Down Sampling: $Hx = (\downarrow 2)(h * x)$

ex. In-painting: $Hx = m \circ x$ m mask.

ex MRI: $Hx = Fx$ Fourier Transform
 $\uparrow$ DFT matrix.

ex. XRAY CT: $Hx = R[x]$ & Radon Transform.

So if $H \in \mathbb{R}^{n \times n}$ square.

Then $\underline{x^* = H^{-1}y = H^{-1}Hx = x.}$

ex. $Hx = h * x$. What is H^{-1} ?

Conv Theorem: $h * x \Leftrightarrow \hat{h} \circ \hat{x} = \mathcal{F}(h) \circ \mathcal{F}(x)$

$\rightarrow F(h * x) = \hat{h} \circ \hat{x} = \text{diag}(\hat{h}) \hat{x} = \text{diag}(\hat{h}) Fx$

$F H x = \text{diag}(\hat{h}) F x \quad \forall x.$

$F H = \text{diag}(\hat{h}) F$

$H = F^{-1} \text{diag}(\hat{h}) F$

$H = F^H \text{diag}(\hat{h}) F$

↳ apply H in form domain
↳ Eigen Decomp of H .

So. What is H^{-1} ?

$$\begin{aligned} H^{-1} &= (F^H \text{diag}(\tilde{h}) F)^{-1} \\ &= F^{-1} \text{diag}(\tilde{h})^{-1} F^{-H} \end{aligned}$$

$$\underline{H^{-1} = F^H \text{diag}\left(\frac{1}{\tilde{h}}\right) F} \quad \leftarrow \text{Assumes } \hat{h} > 0.$$

$$\text{So } x^* = H^{-1} y \quad \checkmark$$

Blur kernel is normalized s.t. $\|h\|_1 = 1$.

so that $\mathcal{F}\{h\}(0) = \sum_{-\infty}^{\infty} h[n] e^{-j\omega n} = \sum_{-\infty}^{\infty} h[n] = 1$.

DL response is 1. 

What if our measurements aren't exact?

i.e. we have some measurement noise?

$$y = Hx + v. \quad \text{Let } v \sim \mathcal{N}(0, \sigma^2 I)$$

$$\begin{aligned} \text{then } x^\diamond = H^{-1}y &= H^{-1}(Hx + v) \\ &= x + H^{-1}v \end{aligned}$$

$$x^\diamond = x + v^*, \quad v^* \sim \mathcal{N}(0, \sigma^2 H^{-1} H^{-T})$$

$$\begin{aligned}
 H^{-1} H^{-T} &= F^H \text{diag}\left(\frac{1}{\hat{h}}\right) F \left(F^H \text{diag}\left(\frac{1}{\hat{h}^*}\right) F \right) \\
 &= F^H \text{diag}\left(\frac{1}{|\hat{h}|^2}\right) F
 \end{aligned}$$

ie. if $\hat{h}$ looks like  ω

$|\hat{h}|^2$  ω

High freq noise amplified!!!

$\Rightarrow$ x^0 explodes in magnitude!

Solution: encode prior information

- $\hookrightarrow$ image magnitude reasonable
- $\hookrightarrow$ penalize large images.

$$x^0 = \underset{x}{\operatorname{argmin}} \quad \underbrace{\frac{1}{2} \|y - Hx\|_2^2}_{\text{Data Fid.}} + \underbrace{\frac{\lambda}{2} \|x\|_2^2}_{\text{Prior}}$$

Solve? Unique Min? Where?

$$\nabla_x (f(x) + g(x)) = 0$$

$$\nabla_x f(x) + \nabla_x g(x) = 0$$

$$H^T (Hx - y) + \lambda x = 0$$

$$(\lambda I + H^T H) x = H^T y$$

$$x = (\lambda I + H^T H)^{-1} H^T y$$

$$= (\lambda F^H F + F^H \operatorname{diag}(|\hat{h}|^2) F)^{-1} H^T y$$

$$= (F^H (\lambda I + \operatorname{diag}(|\hat{h}|^2)) F)^{-1} F^H \hat{h}^* / F y$$

$$= F^H \text{diag} \left(\frac{1}{\lambda + |\hat{h}|^2} \right) \text{diag} (\hat{h}^*) F y$$

$$\boxed{\hat{x} = F^H \text{diag} \left(\frac{\hat{h}^*}{\lambda + |\hat{h}|^2} \right) F y}$$

(Wiener Filter)

↳ Choose λ reasonable s.t.
high freq noise doesn't blow up.

↳ Extend this idea:

- Problem: Loss of information /
approx loss yields unstable solution.

Extreme Example: $y = MFx$.

mask decimates information,
we cannot recover w/out assumptions.

Example: if x is band limited to
 $|\omega| \leq \frac{\pi}{N} \Rightarrow (\downarrow N)x$ has same
freq content.

($\circ$) Prior knowledge allows us to
successfully recover certain signals.

(1.2) Probability Perspective:

ex. let $x \sim p(x)$.

let $y \sim N(\mu, \sigma^2 I)$

then MAP estimator:

$$x^D = \underset{x}{\operatorname{argmax}} p(x|y)$$

$$= \underset{x}{\operatorname{argmax}} \frac{p(y|x)p(x)}{p(y)}$$

Bayes.

$$= \underset{x}{\operatorname{argmax}} p(y|x)p(x)$$

$$= \max_x (\log p(y|x) + \log p(x))$$

$$= \min_x -\log p(y|x) - \log p(x)$$

$$x^D = \min_x \frac{1}{2\sigma^2} \|y - Hx\|_2^2 - \log p(x)$$

$$\text{let } x \sim N(0, \sigma^2 I)$$

$$\text{then } x^* = \min_x \frac{1}{2\sigma^2} \|y - Hx\|_2^2 + \frac{\lambda}{2} \|x\|_2^2$$

$$x^D = \min_x \frac{1}{2} \|y - Hx\|_2^2 + \frac{\lambda}{2} \|x\|_2^2$$

$\leadsto$ Wiener filter.

where $\lambda = \frac{\sigma^2}{P^2}$

if I choose a function $\phi(x)$
as my regularization,
can interpret it as a prior
$$\phi(x) = -\log p(x)$$

$$\Leftrightarrow$$

$$p(x) \propto e^{-\phi(x)}$$

Also, my data fidelity implicitly encodes
a noise model

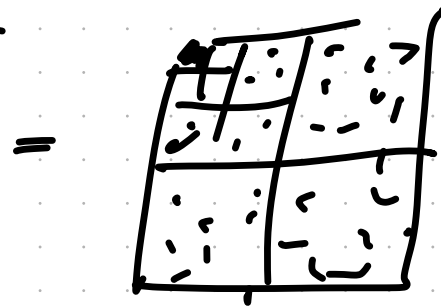
($\epsilon_2 \Leftarrow \text{Gaussian}$)

1.3

Sparse Priors

example:

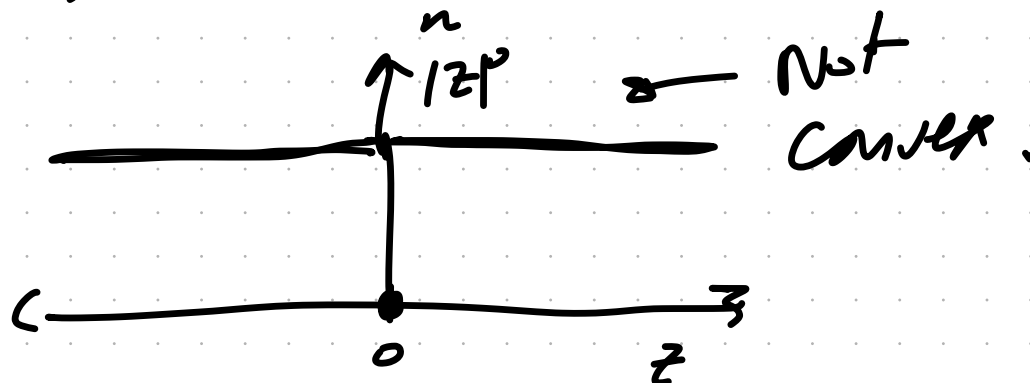
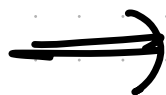
Wavelet (x)

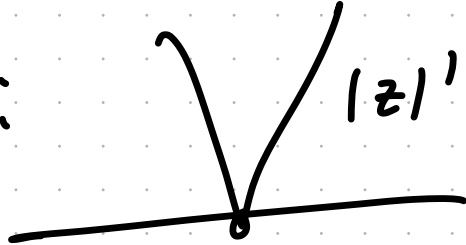


few non-zero
coeff.

Prior: $\Phi(x) = (\# \text{ non-zeros})(Wx)$

$\# \text{ non-zeros}(x) = \sum_n |x_n|^0$



↓ (L1) convex analysis: 

$$\text{So let } \phi(z) = \sum_i |z_i| = \|z\|_1,$$

$$\text{Then } x^* = \underset{x}{\text{amin}} \quad \frac{1}{2} \|y - Hx\|_2^2 + \lambda \|Wx\|_1,$$

Remember W is unitary, so if $z = Wx$,

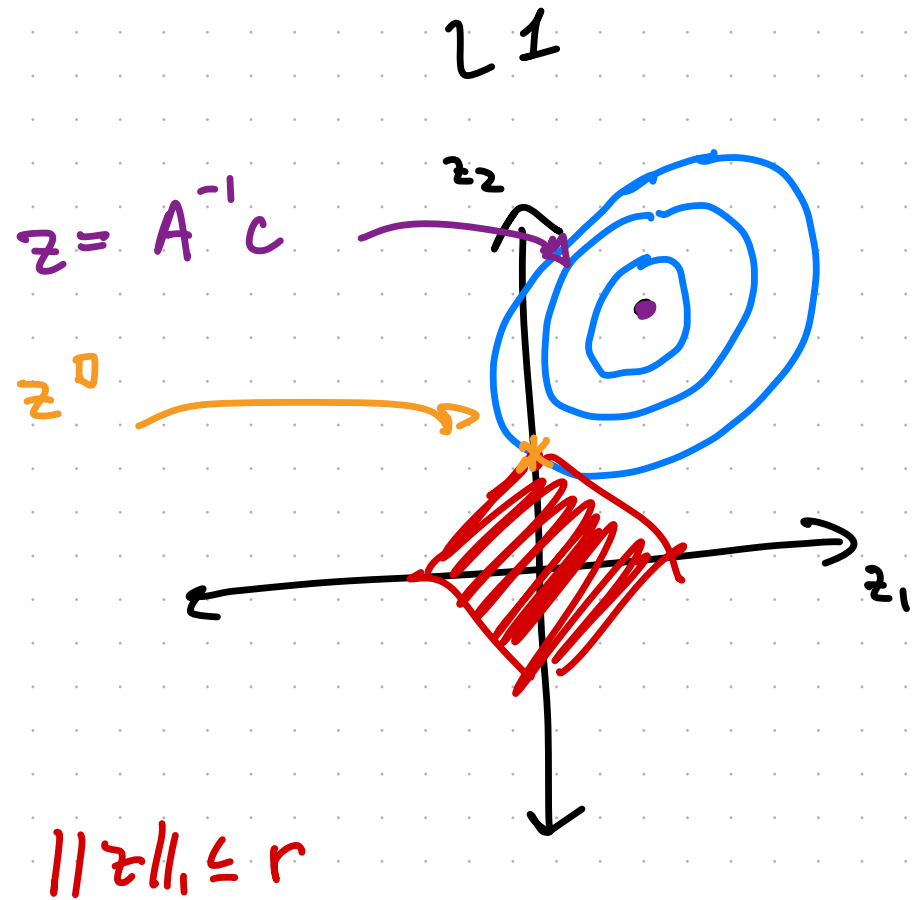
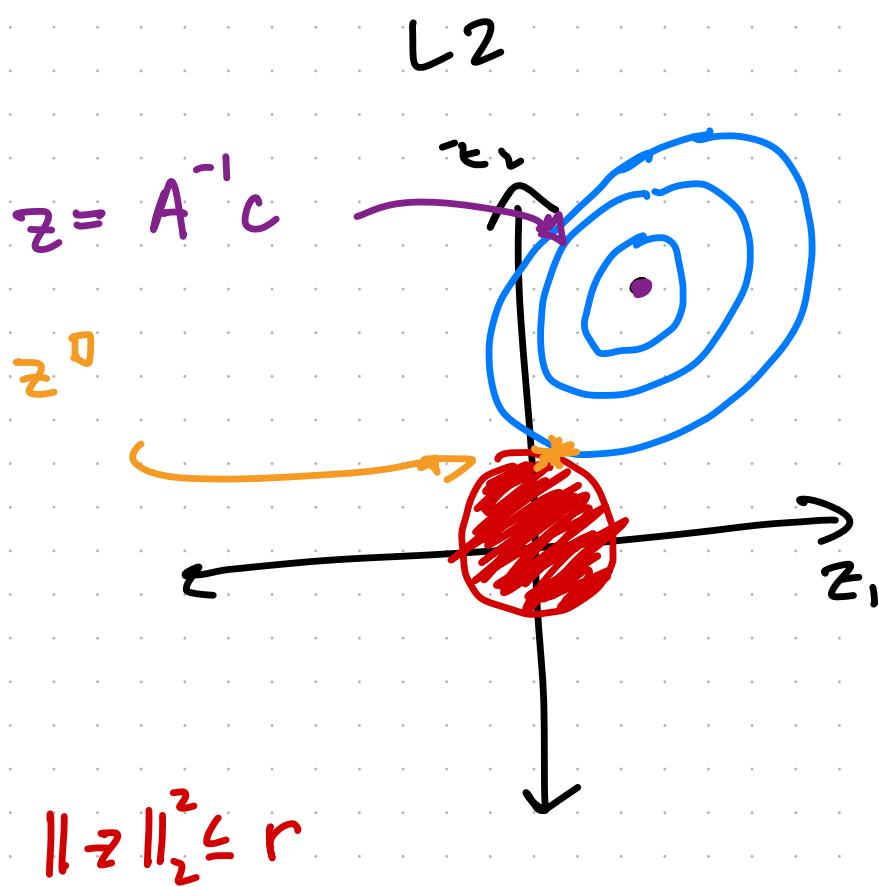
$$x = W^T z.$$

$$\rightarrow z^* = \underset{z}{\text{amin}} \quad \frac{1}{2} \|W(y - HW^T z)\|_2^2 + \lambda \|z\|_1,$$

$$= \underset{z}{\text{amin}} \quad \frac{1}{2} \|c - Az\|_2^2 + \lambda \|z\|_1,$$

$$\equiv \underset{z}{\text{amin}} \quad \mathcal{L}(z).$$

How/Why Do we expect $L1$ to encourage sparsity?



$\Rightarrow$ $L1$ is penalty

Simple Case: $H = I \Rightarrow y = x + v$

$\Rightarrow$ Domain
in the variable

$$Wy = Wx + Wv$$

$$c = z + v_w$$

Domain. $\Leftarrow A = W^T H W = W^T W = I$

$$z^* = \underset{z}{\operatorname{argmin}} \underbrace{\frac{1}{2} \|c - z\|_2^2 + \lambda \|z\|_1}_{\mathcal{L}(z)}$$

$$\begin{aligned} \mathcal{L}(z) &= \frac{1}{2} \sum_i (c_i - z_i)^2 + \lambda \|z\|_1 \\ &= \mathcal{L}_i(z_i) \end{aligned}$$

Can optimize for each z_i individually.

$$z^0 = \underset{z}{\operatorname{argmin}} \quad \frac{1}{2}(c-z)^2 + \lambda|z|$$

(1) assume $z^0 \neq 0$:

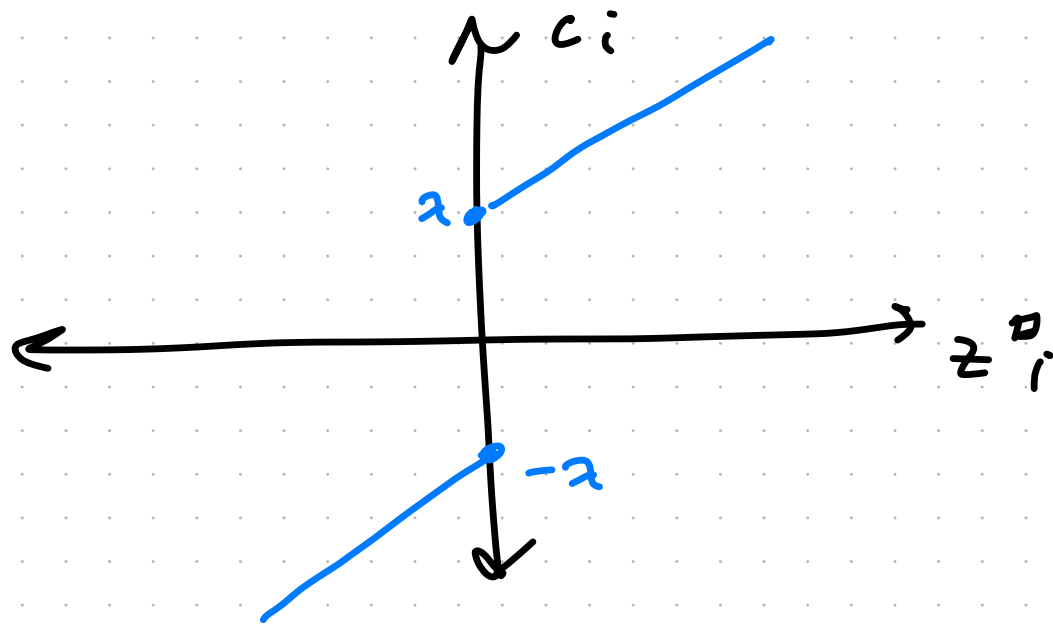
$$\frac{\partial}{\partial z} \left(\frac{1}{2}(c-z)^2 + \lambda|z| \right) = 0$$

$$z^0 - c + \lambda \operatorname{sign}(z^0) = 0$$

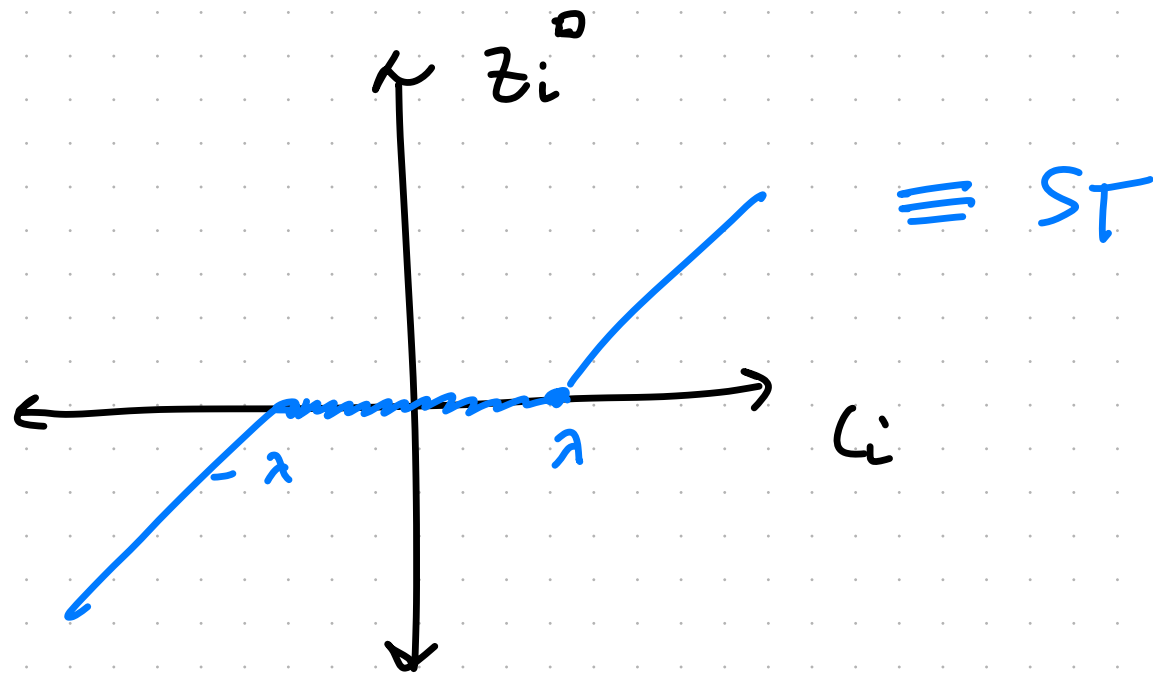
$$c = z^0 + \lambda \operatorname{sign}(z^0)$$

(2) if $z^0 = 0 \Rightarrow z^0 = 0 \quad \text{☺}$

∇



$\mathcal{F}/\dot{\varphi}$



$$z_i^D = \mathcal{S}T_\lambda(c_i) = \text{sign}(c_i) \max(0, |c_i| - \lambda)$$

$$\text{So } \Rightarrow z^D = \underset{z}{\text{amin}} \frac{1}{2} \|C - z\|^2 + \lambda \|z\|,$$

$$z^D = ST_\lambda(C) \quad \leftarrow \text{element-wise}$$

Lets Generalize:

Define the proximal operator of ϕ

$$\text{prox}_{\lambda\phi}(u) = \underset{z}{\text{amin}} \lambda\phi(z) + \frac{1}{2} \|u - z\|_2^2$$

for ϕ (strictly) convex (i.e. unique solution)

So ϕ might not be smooth
(no ctr. derivative).

Can do it as in the case of $\phi = 1.1$,
we can still get a solution.

for smooth ϕ , say

$$\left[\begin{array}{l} x^0 \text{ s.t.} \quad \nabla_x \left(\frac{1}{2} \|u - x\|^2 + \lambda \phi(x) \right) = 0 \\ x - u + \lambda \nabla \phi(x) = 0 \end{array} \right.$$

for non-smooth x , going to
subgradient:

$$x^0 \text{ s.t. } \partial_x \left(\frac{1}{2} \|x - u\|^2 + \lambda \phi(x) \right) \ni 0$$

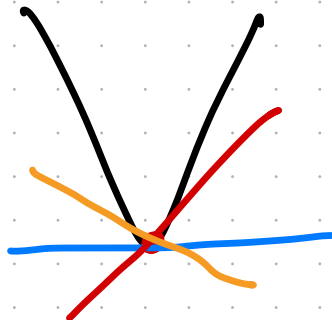
$$0 \in x - u + \lambda \partial \phi(x)$$

what does $\partial \phi$ mean?

set of all slopes below the graph.

ex.

$|z|$



$$(\partial |z|)(z) = \begin{cases} \text{sign}(z), & z \neq 0 \\ [-1, 1], & z = 0 \end{cases}$$

↑ Reduces to Regular derivative
when regular derivative is defined
(i.e. smooth)

↳ we say we're at the minimum
if $0 \in \partial L$

Note: $x = \text{prox}_{\lambda \phi}(u)$,

$$0 \in x - u + \lambda \partial \phi(x)$$

$$0 \in (I + \lambda \partial \phi)x - u$$

$$u \in (I - \lambda \partial \phi)x$$

$$x \in (I - \lambda \partial \phi)^{-1}u$$

but x is the unique minimizer

$$\Rightarrow x = (I - \lambda \partial \phi)^{-1}u$$

$$\Rightarrow \text{prox}_{\lambda \phi}(u) = (I - \lambda \partial \phi)^{-1}u$$

Now let's restrict: $H \neq \mathbb{R}$, $\phi = \|\cdot\|$,

$$z^0 = \arg \min \underbrace{\frac{1}{2} \|C - Az\|_2^2}_{f(z)} + \underbrace{\lambda \phi(z)}_{g(z)}$$

$$0 \in \eta \partial (f(z^0) + g(z^0))$$

$$0 \in \eta \nabla f(z^0) + \eta \partial g(z^0)$$

$$0 \in \eta \nabla f(z^0) - z^0 + z^0 + \eta \partial g(z^0)$$

$$(\mathbb{I} - \eta \nabla f)(z^0) \in (\mathbb{I} + \eta \partial g)(z^0)$$

$$z^1 \in (\mathcal{I} + \eta g)^{-1} (\mathcal{I} - \eta \nabla f)(z^0)$$

$$z^1 = \text{prox}_{\eta g} \left(\underbrace{z^0 - \eta \nabla f(z^0)}_{\text{Gradient Descent on } f} \right)$$


proximal
update
 w/ g .

Gradient
Descent. on f


Proximal Gradient
Descent.

When $H = \mathbb{I}$, $\Phi(u) = \|Wu\|_1$,

↳ Recast as a wavelet coeff
recovery problem:

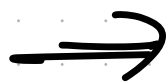
$$x^0 = W^T z^0 \quad \leftarrow \text{IWT}$$

$$z^0 = \underset{z}{\operatorname{argmin}} \quad \underbrace{\frac{1}{2} \|c - Az\|_2^2}_f + \underbrace{\lambda \|z\|_1}_g$$

$$\nabla_z f = A^T (Az - c)$$

$$\operatorname{prox}_{\eta g}(u) = \operatorname{prox}_{\eta \lambda \|\cdot\|_1}(u) = S_{T_\lambda}(u)$$

iterative



$$z^{k+1} = S_{\eta+}^T \left(z^k - \eta A^T (A z^k - c) \right)$$



ISTA!

More Generally we can solve

any $x^0 = \underset{x \in \mathcal{L}}{\operatorname{amin}} f(x) + g(x)$

where f smooth and we have

(expression for $\operatorname{prox}_{\eta g}$

↳ This becomes difficult when $g(x)$ is not separable,

ex. when a transform domain is not orthogonal.

ex. $x^* = \underset{x}{\operatorname{argmin}} \frac{1}{2} \|y - Hx\|^2 + \phi(Dx)$

$\Rightarrow$ ADMM:

|

↓
Proximal Method that
Solves

$$x^0, z^0 = \underset{x, z}{\operatorname{amin}} f(x) + g(z)$$

s.t. $Ax + Bz = c$

$$x^{n+1} = \underset{x}{\operatorname{amin}} f(x^n) + \frac{1}{2} \|Ax^n + Bz^n - c + u^n\|^2$$

$$z^{n+1} = \underset{z}{\operatorname{amin}} g(z^n) \quad \dots$$

$$u^{n+1} =$$

Primal Dual Spleh

$$\min_x f(x) + g(Dx)$$

$$\min_x f(x) \quad \max_z z^T Dx - g^*(z)$$

—
fenchel conjugate

$$\min_x \max_z f(x) + \underbrace{z^T Dx}_{\text{smooth}} - \underbrace{g^*(z)}_{\text{non smooth!}}$$

↓
non smooth?

↓
non smooth!



Do PGD step on x
Do PGA step on z
repeat

$$x^{k+1} = \text{prox}_{\tau f} (x^k - \tau D^T z^k)$$

$$z^{k+1} = \text{prox}_{\sigma g^*} (z^k + \sigma D x^{k+1})$$

where we use moreau's identity:

$$\left[v = \text{prox}_{g^*}(v) + \text{prox}_g(v) \right]$$

$$^2 \left[g(y) = \max_z y^T z - g^*(z) \right]$$